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Abstract. Compact size and fast imaging abilities are key requirements for the clinical implementation of an optical coherence tomography (OCT) system. Among the various small-sized technology, a microelectromechanical system (MEMS) scanning mirror is widely used in a miniaturized OCT system. However, the complexities of conventional MEMS fabrication processes and relatively high costs have restricted fast clinical translation and commercialization of the OCT systems. To resolve these problems, we developed a two-axis polydimethylsiloxane (PDMS)-based MEMS (2A-PDMS-MEMS) scanning mirror through simple processes with low costs. It had a small size of 15 × 15 × 15 mm³, was fast, and had a wide scanning range at a low voltage. The AC/DC responses were measured to evaluate the performance of the 2A-PDMS-MEMS scanning mirror. The maximum scanning angles were measured as ±16.6 deg and ±11.6 deg along the X and Y axes, respectively, and the corresponding field of view was 29.8 mm × 20.5 mm with an optical focal length of 50 mm. The resonance frequencies were 82 and 57 Hz along the X and Y axes, respectively. Finally, in vivo B-scan and volumetric OCT images of human fingertips and palms were successfully acquired using the developed SD-OCT system based on the 2A-PDMS-MEMS scanning mirror. © 2016 Society of Photo-Optical Instrumentation Engineers (SPIE) [DOI: 10.1117/1.JBO.21.10.106001] Keywords: optical coherence tomography; microelectromechanical system scanning mirror; polydimethylsiloxane.

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Optical coherence tomography (OCT) is considered an essential noninvasive optical imaging technique for providing microstructural and functional information with respect to biological tissues in real time. Advancements in broadband light sources, sensitive detectors, and real-time computing techniques enabled OCT to achieve excellent performance with high spatial resolution and real-time volumetric display. Thus, it is a premier medical instrument for diagnosing ophthalmic diseases. In addition, clinical researchers in various medical fields, including dermatology, cardiology, oncology, and gastroenterology, utilize the OCT technique in alternative promising medical diagnostic devices. Furthermore, OCT is also utilized in nonmedical applications, such as nondestructive inspection tools in industrial fields for thin film-based products and agriculture.

The acquisition of cross-sectional and volumetric OCT data involves scanning of sample OCT beams at the desired target region. However, the use of motorized stages in the first OCT scanner is limited because of its large size and low scanning speed, which cause motion artifacts. These issues necessitated advanced scanners for clinical implementation. Recently, galvanometer scanners were utilized in real-time commercial OCT systems because of their linear scanning patterns, fast scanning abilities, and precise positioning. However, the use of the galvanometer scanners to develop endoscopic or small-sized handheld probes for imaging internal organs (e.g., esophagus and bronchus) is difficult owing to their oriented configurations containing two-axial (X and Y axes) servo motors and relatively large size of the galvanometer scanners. To compensate these bottlenecks, various types of microelectromechanical system (MEMS) scanners (e.g., electrostatic, electromagnetic, piezoelectric, and electrothermal types), were introduced for endoscopic and handheld probes. Although their advantages include small form factors and high speed scanning abilities, the complex fabrication process, relatively high costs, and suitable operating conditions requirements present drawbacks for true clinical implementation and commercialization. Particularly, normal silicon-based MEMS scanners required various manufacturing procedures, including photolithography, thin-film deposition, masking, etching, and metallization. Hence, these multifarious fabrication steps resulted in complexities in the MEMS scanner structures and high manufacturing costs. Moreover, it was difficult to use the MEMS scanners in humid environments.

In this study, a two-axis polydimethylsiloxane (PDMS)-based electromagnetic MEMS (2A-PDMS-MEMS) scanning mirror using a simple and cost-effective soft-lithography microfabrication process was developed. The performance of the...
2A-PDMS-MEMS scanning mirror, such as the scanning pattern and the AC/DC response, was measured. Finally, the 2A-PDMS-MEMS scanning mirror could be driven under a wide range of AC/DC conditions given the considerable elasticity of the PDMS body. Four neodymium magnets were fixed inside the PDMS body and strong laboratory-made electromagnets were aligned with each magnet. Finally, the PDMS structural layer and the block of electromagnets were assembled with an adhesive. Electromagnetic attractive and repulsive forces between the neodymium magnets in the movable PDMS body and electromagnets in an aluminum block [Fig. 1(c)] were utilized to create torsional scanning motions of the mirror. The size of the fabricated 2A-PDMS-MEMS scanning mirror was 15 mm × 15 mm × 15 mm along the $X$, $Y$, and $Z$ axes, respectively. Figure 1(d) shows the photograph of the 2A-PDMS-MEMS scanning mirror.

Figure 2(a) shows an experimental setup to demonstrate the scanning characteristics of the fabricated 2A-PDMS-MEMS scanning mirror, including the maximum scanning angle and resonance frequency under the DC/AC conditions. The driving voltages for the electromagnets along the $X$ and $Y$ axes were controlled by the analog outputs of a data acquisition system (NI PCIe-6321, National Instruments, United States). A current amplifier circuit with a high-current op-amp (OPA2544, Texas Instruments, United States) was used to provide sufficient current to the coils. At various amplitudes and frequencies of the driving voltage, the maximum scanning angle $\theta_{\text{max}}$ was determined using Eq. (1) as follows:

$$\theta_{\text{max}} = 2 \tan^{-1}\left(\frac{l}{d}\right),$$

where $d$ is the vertical distance between the mirror and the sample and $l$ is the measured scanning length. First, the scanning angle was obtained by increasing the driving voltage from 0 V to 10 V at the DC condition [Fig. 2(b)]. As shown in the linear fitting from the experimental data, the applied voltage and the scanning angle displayed a linear relationship. Note that the resistance change of each electromagnet is negligible (i.e., <1% with a DC voltage of 10 V). The maximum scanning angles along the $X$ and $Y$ axes were ±16.6 deg at 4 V and ±11.6 deg at 10 V, respectively. To avoid sticking of the permanent magnet to the electromagnet, the maximum applied voltages are limited to 4 and 10 V along the $X$ and $Y$ axes, respectively. A thick torsional hinge along the $Y$ axis resulted in higher stiffness, which in turn resulted in a smaller scanning

### Table 1 Design parameters of the 2A-PDMS-MEMS scanning mirror.

<table>
<thead>
<tr>
<th>Neodymium magnets</th>
<th>Electromagnet</th>
<th>Hinge—$X$ axis</th>
<th>Hinge—$Y$ axis</th>
<th>Mirror plate</th>
</tr>
</thead>
<tbody>
<tr>
<td>Diameter</td>
<td>1 mm</td>
<td>3 mm</td>
<td>0.5 mm</td>
<td>1 mm</td>
</tr>
<tr>
<td>Thickness</td>
<td>0.5 mm</td>
<td>11 mm</td>
<td>1 mm</td>
<td>1 mm</td>
</tr>
<tr>
<td>Magnetic force</td>
<td>1500 G</td>
<td>300 G at 5 V</td>
<td>Thickness</td>
<td>Thickness</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1 mm</td>
<td>1 mm</td>
</tr>
</tbody>
</table>
angle than that along the X axis. The scanning angles along the X and Y axes were measured by increasing the driving frequency to show the frequency response at a fixed voltage of 1 V_p-p [Fig. 2(c)]. The resonance frequencies of the MEMS scanning mirror were 82 and 57 Hz along the X and Y axes, respectively. Compared to shear modulus of silicon (e.g., ~80 GPa) in conventional MEMS technology, the low shear modulus of PDMS (e.g., ~250 kPa) mainly resulted in low resonance frequencies, which were exactly in the operational range of the fabricated scanning mirror (i.e., 50 to 100 Hz).

Both raster and Lissajous scanning patterns were successfully demonstrated [Figs. 2(d) and 2(e)] because of the AC/DC scanning characteristics. The raster scanning pattern is obtained at the following driving conditions: 2 V at 4 Hz along the X-axis and 3 V at 96 Hz along the Y axis, respectively. The Lissajous scanning pattern is obtained at the following driving conditions: 3 V at 81 Hz (\(\Phi = 0\) deg) along the X-axis and 3 V at 74 Hz (\(\Phi = 0\) deg) along the Y-axis, respectively. In the raster scanning mode for a dense pixel number, the linear and high scanning angles of the mirror are preferred at the DC condition. Although B-scan and volumetric images could be easily acquired using the raster scan, fast and wide imaging is possible using the Lissajous scan. In this study, the raster scan was used only to obtain accurate B-scan and volumetric OCT images. The 2A-PDMS-MEMS scanning mirror has the advantages of a larger field of view (FOV) at smaller driving voltages compared with the commercial MEMS mirror used in other OCT systems. For instance, the maximum FOV of the system is 29.8 mm x 20.5 mm along the X and Y axes with an optical focal length of 50 mm and a driving voltage of 4 and 10 V along X and Y axes, respectively. By contrast, a commercial product with a 2.4-mm mirror size has the FOV of 10 mm x 10 mm with a driving voltage range of 0 to 100 V. The measured current flow in coils is about 21 mA at 2 V and 53 mA at 5 V during in vivo imaging. Although this current flow is high and causes damages in tissues with direct contact, the coils in the MEMS scanner are fully electrically insulated. In addition, the current flows in the previously reported OCT MEMS scanners range from 20 to 100 mA. Thus, we believe that the electrical power of our system is low enough for biomedical applications.

The conventional SD-OCT system was implemented to prove the feasibility of the 2A-PDMS-MEMS scanning mirror in the OCT. However, the existing galvanometer scanning

![Fig. 2 Scanning characteristics of 2A-PDMS-MEMS scanning mirror. (a) Experimental setup; (b) maximum scanning angle versus input voltage; (c) frequency response at AC voltage; (d) raster scan pattern; and (e) lissajous scan pattern. AMP, amplifier; DAQ, data acquisition board.](image-url)
mirror was replaced with the 2A-PDMS-MEMS scanning mirror. Figure 3(a) shows a schematic of the SD-OCT system based on the 2A-PDMS-MEMS scanning mirror. A broadband light beam (SLD-351-HP3, Superlum, Ireland) with a center wavelength of 860 nm, bandwidth of 59.6 nm, and output power of 16.5 mW was delivered to the sample and the reference arms through a 50:50 optical coupler (F850-40-50-APC, Thorlabs). The sample and reference arms were composed of identical collimators (F260APC-B, Thorlabs) and objective lenses (AC254-050-B, Thorlabs) to compensate for the dispersion. The 2A-PDMS-MEMS scanning mirror was applied to the sample arm for volumetric optical scanning. The interference signals were generated at different depths following the incident light reflected from both arms. The signals were captured by a laboratory-made line-camera-based spectrometer. The spectrometer consisted of a 2-in. achromatic lens (AC508-075-B, Thorlabs), a grating (HD 1800 l/mm, Wasatch Photonics), and a line-scan camera (SpL4096-140Km, Basler, Germany). The recorded OCT signals were converted to digital data through a frame grabber (PCIe-1429, National Instruments). The converted data were transformed into B-scan OCT images after additional signal processing involving k-linearization26 and fast Fourier transform was performed via LabView software. The spatial resolution was measured using a carbon fiber to evaluate the performance of the SD-OCT system. The measured lateral and axial resolutions were 23 and 7 μm, which are close to the theoretical lateral (i.e., 19 μm) and axial (i.e., 6 μm) resolutions [Figs. 3(b) and 3(c)]. The sensitivity measured from a mirror sample is 108 dB. Finally, B-scan and volumetric OCT images of the human finger area were obtained. All human experimental procedures were conducted in accordance with protocols approved by the institutional review board of POSTECH. To acquire OCT images of a human finger, we recruited healthy volunteers. A sine waveform with a frequency of 11.8 Hz and an input voltage of 2 V were applied to obtain the B-scan OCT images along the X axis. A sawtooth waveform with a frequency of 0.06 Hz and an input voltage of 5 V were utilized along the Y axis to operate a volumetric imaging mode. The acquired pixel size is 500 × 200 along the X and Y axes, respectively. The imaging time was 17 s, and the FOV of the acquired image was 8 mm × 8 mm along the X and Y axes. The volumetric image data were reconstructed through a commercial 3-D rendering software (Amira 6, FEI).

Figures 4(a) and 4(b) indicate the OCT images of the finger-tips and palm, respectively. Figures 4(i), 4(ii), 4(iii), and Ref. 15 illustrate B-scan OCT images along the X and Z axes, B-scan OCT images along the Y and Z axes, en-face OCT images along the X and Y axes, and volumetric rendering OCT images, respectively. The B-scan OCT images clearly visualized the structural information of the skin surface, the epidermis, and
the dermis. In addition, the fingertip patterns and sweat ducts were observed in Fig. 4(b).

The two-axis electromagnetic MEMS scanning mirror using a flexible PDMS material was successfully demonstrated. This novel MEMS scanner provided a relatively cost effective and simple fabrication process for repetitive production when compared with the conventional MEMS process. Then, the characteristics of the 2A-PDMS MEMS scanning mirror, including the scanning pattern and the AC/DC response, were measured. Finally, the 2A-PDMS MEMS scanning mirror integrated with the SD-OCT system was evaluated by scanning a human subject’s fingertips and palm. The 2A-PDMS-MEMS scanning mirror is expected to play a crucial role in diverse optical imaging systems for fast translation and commercialization. Future research that could result in further improvements include the following: (1) compensation of a nonlinear and asymmetric scanning pattern of a scanning mirror, (2) utilization of multimodal optical imaging systems to provide comprehensive biological information, (3) further reduction in the size of the 2A-PDMS-MEMS scanning mirror for adapting an endoscopic regime, and (4) fabrication of a MEMS scanner with high resonance frequency to avoid environmental noises and achieve high speed imaging. Particularly, it is expected that a nonlinear scanning pattern, hysteresis, and cross-talks between two axes can be compensated by well-known feedback loop based control methods.

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References


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