

Design of LIDAR wide field of view receiver based on MEMS micro-mirror and high sensitivity APD (Erratum)

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[Proceedings Volume 11781, 4th Optics Young Scientist Summit \(OYSS 2020\)](#); 117811U (2021)
<https://doi.org/10.1117/12.2600830>

Event: 4th Optics Young Scientist Summit (OYSS 2020), 2021, Ningbo, China

Online Publication Date: 28 February 2021

Erratum Published: 10 May 2021

A revised version of this manuscript was published on 10 May 2021. Details of the revision are provided in the text that accompanies this Erratum. The original paper has been updated.